

PRESENTATION TITLE

Author

Date

Paper available at <https://github.com/pmichailat/latex-presentation>

SLIDE TITLE

- lorem ipsum dolor sit amet
- consectetur adipiscing elit
- sed do eiusmod tempor incididunt
 - ut labore et dolore magna aliqua
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- quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat
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SLIDE WITH ALERTS

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SLIDE WITH ALERTS

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SLIDE WITH SYMBOLS

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4. veniam quis nostrud exercitation \downarrow
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6. quis nostrud exercitation | laboris nisi ut aliquip | ex ea commodo
consequat

SLIDE WITH BUTTON

1. excepteur sint occaecat cupidatat non proident, sunt in culpa qui officia deserunt mollit anim id est laborum
2. veniam quis nostrud exercitation: $u^* = \Lambda$
3. veniam quis nostrud exercitation: $u^* = \Gamma - \zeta$
4. veniam quis nostrud exercitation: $u^* = \Omega - \eta$
5. quis nostrud exercitation laboris nisi ut aliquip ex ea commodo consequat

▶ Go to a first backup slide

▶ Go to another backup slide

FIRST BACKUP SLIDE

- lemma: lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua:
- theorem: ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat
- corollary: duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur

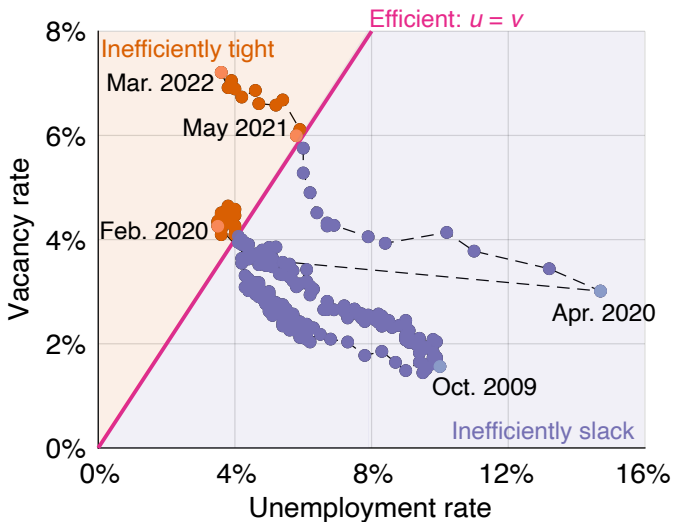
ANOTHER BACKUP SLIDE

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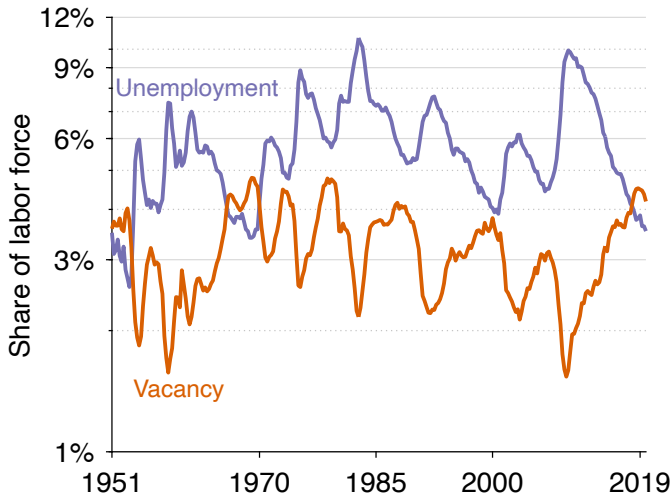
▶ [Return to main slide](#)

SECTION TITLE

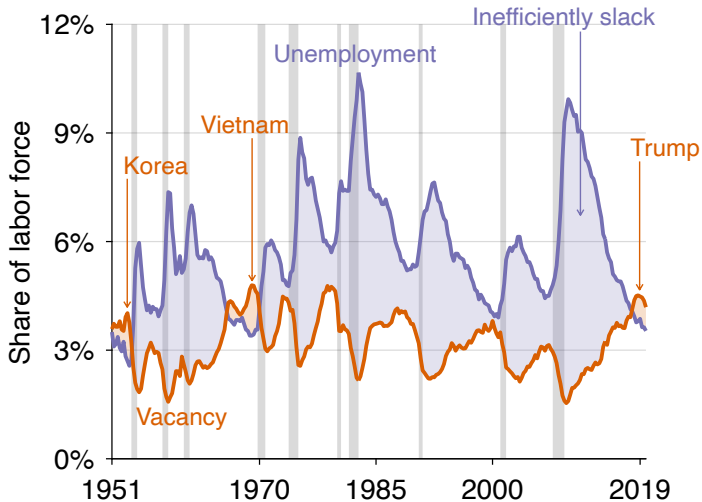
SLIDE WITH GRAPH



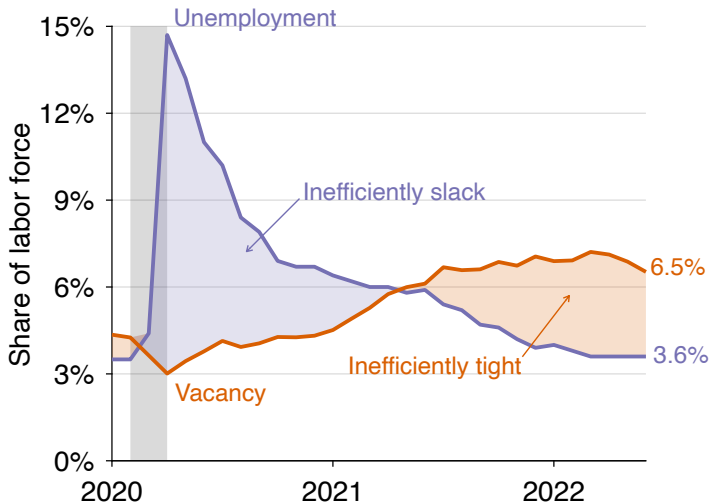
SEVERAL GRAPHS (USE TITLE AS CAPTION)



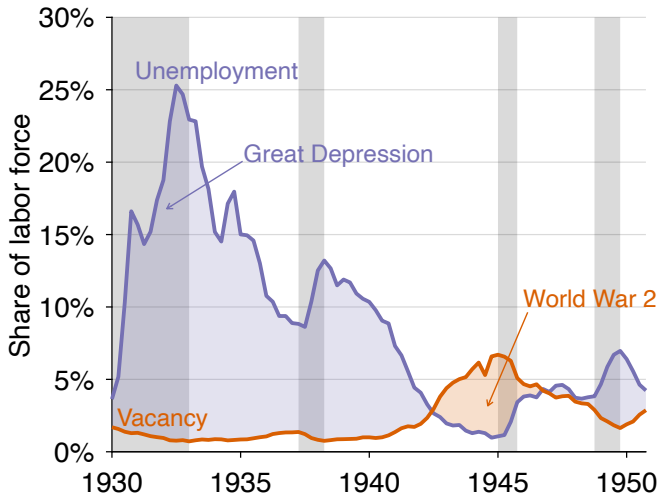
SEVERAL GRAPHS



SEVERAL GRAPHS



SEVERAL GRAPHS



SLIDE WITH MATH

- excepteur sint occaecat cupidatat $j \in \mathbb{R}$:

$$\int_0^{\infty} e^{-\delta t} \ln(c_j(t)) + \mathcal{U}(b_j(t) - \mathcal{B}(t)) - \frac{\zeta}{2} h_j(t) - \frac{\gamma}{2} \pi_j(t)^2 dt$$

- irure dolor: $c_j(t) = \int_0^1 c_{jk}(t)^{(\epsilon-1)/\epsilon} dk$
 - mollit anim id est: $\mathcal{B}(t) = \int_0^1 [b_j(t)]^\sigma dj$
 - est laborum: $\pi_j(t) = \dot{p}_j(t)/p_j(t)$
- in reprehenderit in voluptate:

$$\dot{b}_j(t) = i(t)b_j(t) + p_j(t)y_j(t) - \int_0^1 p_k(t)c_{jk}(t) dk$$

- lorem ipsum dolor sit amet, consectetur adipisicing elit

ANOTHER SECTION

SLIDE WITH TABLE AND ALERTS AND A LONG TITLE (USE TITLE AS CAPTION)

	$m < 0$	$m = 0$	$m > 0$
$u > u^*$	$g/c < (g/c)^*$	$g/c = (g/c)^*$	$g/c > (g/c)^*$
$u = u^*$	$g/c = (g/c)^*$	$g/c = (g/c)^*$	$g/c = (g/c)^*$
$u < u^*$	$g/c > (g/c)^*$	$g/c = (g/c)^*$	$g/c < (g/c)^*$
$\alpha = \beta$	$\phi \approx \mu$	$\omega < \theta$	\mathbb{Q} or \mathbb{N}

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$u = u^*$	$g/c = (g/c)^*$	$g/c = (g/c)^*$	$g/c = (g/c)^*$
$u < u^*$	$g/c > (g/c)^*$	$g/c = (g/c)^*$	$g/c < (g/c)^*$
$\alpha = \beta$	$\phi \approx \mu$	$\omega < \theta$	\mathbb{Q} or \mathbb{N}
